# SOME RESULTS ON HARMONIC MAPS 

MIN-CHUN HONG

Min-Chun Hong, Department of Mathematics, The University of Queensland, Brisbane, QLD 4072, Australia.
E-mail: hong@maths.uq.edu.au
$\|\|\|$


#### Abstract

In this note, we will outline the classical results of Eells-Sampson 7] on the harmonic heat flow, Sacks-Uhlenbeck [26] in homotopy classes and Schoen-Uhlenbeck [28] on the partial regularity of minimizing harmonic maps. This note also contains a new proof of the Sacks-Uhlenbeck result 26] by using an estimate of Trudinger 34], which improved the result of Moser in 23].


## 1. Introduction

The theory of harmonic maps provides a prototype for many complex physical theories including the $\sigma$-model, superconductivity, and string theory. The theory of harmonic maps has many important applications to geometry and topology. Motivated by the seminal work of Eells and Sampson [7] on the harmonic map flow, Donaldson [6] established the important Donaldson-Uhlenbeck-Yau theorem by using the Yang-Mills flow, and Hamilton in [14] established many pioneering results on the Ricci flow in order to settle the Poincare conjecture.

One of the important tasks on harmonic maps is to deal with the very challenging Eells-Sampson question (e.g. [8]). More precisely, let $u_{0}$ be a given smooth map from $M$ to $N$. Can $u_{0}$ be deformed to a harmonic map in its homotopy class?

Received July 22, 2013 and in revised form January 14, 2014.
AMS Subject Classification: 58J05, 58J35.
Key words and phrases: Harmonic maps.

The Eells-Sampson question is a question of establishing existence of a smooth harmonic map representative in a fixed homotopy class of maps between two manifolds. Main purpose of this note is to discuss three classical results related to this question. We will discuss this question for the case that the target manifolds $N$ have non-positive sectional curvature and some results of minimizing the Dirichlet energy. More precisely, in Section 3, we will outline some key proofs of the classical results of Eells-Sampson [7] on the harmonic heat flow. In Section 4, we will discuss the result of SacksUhlenbeck [26] in homotopy classes in $2 D$. In particular, we will present some new proofs on the Sacks-Uhlenbeck result [26] by using an estimate of Trudinger [34], which improved the Moser-Harnack estimate [23]. In Section 5, we will outline some key proofs of Schoen-Uhlenbeck [28] on the partial regularity of minimizing harmonic maps (see also Giaquinta-Giusti [10]). This note was lectured by the author in the Winter School on Geometric Partial Differential Equations at Brisbane, Australia from 2-13 July 2012.

Finally, I would like to dedicate this paper to Professor Neil Trudinger on the occasion of his 70th birthday.

## 2. Harmonic Maps between Manifolds

Let $M$ be a n-dimensional Riemannian manifold (with or without boundary) with a smooth Riemannian metric $g$. In a local coordinates around fixed point $p \in M, g$ can be represented by

$$
g=g_{i j} d x_{i} \otimes d x_{j}
$$

where $\left(g_{i j}\right)$ is a positive definite symmetric $n \times n$ matrix. Let $\left(g^{i j}\right)=\left(g_{i j}\right)^{-1}$ be the inverse matrix of $\left(g_{i j}\right)$ and the volume element of $(M ; g)$ is

$$
d v_{g}=\sqrt{|g|} d x
$$

where $|g|=\operatorname{det}\left(g_{i j}\right)$. Let $(N ; h)$ be another $l$-dimensional compact Riemannian manifold without boundary (isometrically embedded into $\mathbb{R}^{k}$ ), with a smooth Riemannian metric $h$.

For a map $u: M \rightarrow N$, its Dirichlet energy functional is defined by

$$
E(u)=\int_{M} e(u) d v_{g},
$$

where the density function $e(u)$ is given by

$$
e(u)(x)=\frac{1}{2}|\nabla u(x)|^{2}=\frac{1}{2} \sum_{\alpha, \beta, i, j} g^{i j}(x) h_{\alpha \beta}(u(x)) \frac{\partial u^{\alpha}}{\partial x_{i}} \frac{\partial u^{\beta}}{\partial x_{j}} .
$$

A smooth map $u$ from $M$ to $N$ is said to be a harmonic map ([8]) if $u$ is a critical point of the Dirichlet energy functional $E$; i.e. it satisfies

$$
\triangle_{M} u+A(u)(\nabla u, \nabla u)=0
$$

in $M$, where $\triangle_{M}$ is the Laplacian operator with respect to the Riemannian metric of $M$ and $A$ is the second fundamental form of $N$.

Next, we will give details to get the harmonic map equations.
We recall that a Riemannian manifold $M$ is a smooth manifold which is equipped with a Riemannian metric $g$; i.e. for each tangent space $T_{x} M$, there is an inner product $\langle\cdot, \cdot\rangle$. In local coordinates,

$$
g_{i j}:=\left\langle\frac{\partial}{\partial x^{i}}, \frac{\partial}{\partial x^{j}}\right\rangle
$$

For $X, Y, Z \in C^{\infty}(T M)$, the connection $\nabla$ satisfies

$$
X\langle Y, Z\rangle=\left\langle\nabla_{X} Y, Z\right\rangle+\left\langle Y, \nabla_{X} Z\right\rangle
$$

The connection, which satisfies the above identity, is called Riemannian. In local coordinates, the Christoffel symbols are defined by

$$
\nabla_{\frac{\partial}{\partial x^{i}}}\left(\frac{\partial}{\partial x^{j}}\right)=\Gamma_{i j}^{k} \frac{\partial}{\partial x^{k}}
$$

More precisely, the Christoffel symbols $\Gamma_{i j}^{k}$ can be expressed by

$$
\Gamma_{i j}^{k}:=\frac{1}{2} g^{k l}\left(\frac{\partial g_{l j}}{\partial x^{i}}+\frac{\partial g_{i l}}{\partial x^{j}}-\frac{\partial g_{i j}}{\partial x^{l}}\right) .
$$

We recall that the curvature tensor of Levi-Civita connection $R$ is given by

$$
R(X, Y) Z=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z
$$

for $X, Y, Z \in C^{\infty}(T M)$. In local coordinates,

$$
R\left(\frac{\partial}{\partial x^{i}}, \frac{\partial}{\partial x^{j}}\right) \frac{\partial}{\partial x^{l}}=R_{l i j}^{k} \frac{\partial}{\partial x^{k}}
$$

We set

$$
R_{k l i j}:=g_{k m} R_{l i j}^{m}=\left\langle R\left(\frac{\partial}{\partial x^{i}}, \frac{\partial}{\partial x^{j}}\right) \frac{\partial}{\partial x^{k}}, \frac{\partial}{\partial x^{l}}\right\rangle
$$

In local coordinates, we have

$$
\begin{equation*}
R_{l i j}^{k}=\left(\frac{\partial \Gamma_{j l}^{k}}{\partial x^{i}}-\frac{\partial \Gamma_{i l}^{k}}{\partial x^{j}}+\Gamma_{i m}^{k} \Gamma_{j l}^{m}-\Gamma_{j m}^{k} \Gamma_{i l}^{m}\right) \tag{1}
\end{equation*}
$$

Let $N$ be another compact Riemannian manifold with a metric $h$.
Let $u=\left(u^{1}, \ldots, u^{l}\right)$ be a $C^{1}$-map from $M$ to $N$. Intrinsically, the differential $d u$ of $u$ is given (see [8] or [18]) by

$$
d u=\frac{\partial u^{\alpha}}{\partial x^{i}} d x^{i} \otimes \frac{\partial}{\partial u^{\alpha}}
$$

which can be considered as a section of the bundle $T^{*} M \otimes u^{-1}(T N)$. Then we define the energy density

$$
e(u)=\frac{1}{2}\langle d u, d u\rangle_{T^{*} M \otimes u^{-1}(T N)}=\frac{1}{2} g^{i j} h_{\alpha \beta}(u) \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial u^{\beta}}{\partial x^{j}} .
$$

We define the energy of $u$ as

$$
E(u):=\int_{M} e(u) d v_{g}
$$

Assume that $u$ is a critical point of $E$. Then for all admissible variation $\varphi \in C_{0}^{\infty}(M)$

$$
\left.\frac{d}{d t} E(u+t \varphi)\right|_{t=0}=0
$$

It implies that

$$
0=\int_{M}\left(g^{i j} h_{\alpha \beta} \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial \varphi^{\beta}}{\partial x^{j}}+\frac{1}{2} g^{i j} h_{\alpha \beta, u^{\sigma}} \varphi^{\sigma} \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial u^{\beta}}{\partial x^{j}}\right) \sqrt{|g|} d x
$$

$$
\begin{aligned}
= & -\int_{M} \frac{\partial}{\partial x^{j}}\left(\sqrt{|g|} g^{i j} \frac{\partial u^{\alpha}}{\partial x^{i}}\right) h_{\alpha \beta} \varphi^{\beta} d x-\int_{M} g^{i j} \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial u^{\sigma}}{\partial x^{j}} h_{\alpha \beta, u^{\sigma}} \varphi^{\beta} \sqrt{|g|} d x \\
& +\int_{M} \frac{1}{2} g^{i j} h_{\alpha \beta, u^{\sigma}} \varphi^{\sigma} \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial u^{\beta}}{\partial x^{j}} \sqrt{|g|} d x
\end{aligned}
$$

Put $\eta^{\alpha}=h_{\alpha \beta} \varphi^{\beta}$; i.e. $\varphi^{\beta}=h^{\gamma \beta} \eta^{\gamma}$. Then

$$
\begin{aligned}
0= & -\int_{M} \frac{\partial}{\partial x_{j}}\left(\sqrt{|g|} g^{i j} \frac{\partial u^{\gamma}}{\partial x^{i}}\right) \eta^{\gamma} d x \\
& -\frac{1}{2} \int_{M} g^{i j} h^{\gamma \sigma}\left(h_{\alpha \sigma, u^{\beta}}+h_{\sigma \beta, u^{\alpha}}-h_{\alpha \beta, u^{\sigma}}\right) \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial u^{\beta}}{\partial x^{j}} \eta^{\gamma} \sqrt{|g|} d x
\end{aligned}
$$

which implies

$$
\triangle_{M} u=\frac{1}{\sqrt{|g|}} \frac{\partial}{\partial x_{i}}\left(\sqrt{|g|} g^{i j} \frac{\partial u}{\partial x_{i}}\right)=-A(u)(\nabla u, \nabla u)
$$

where $A(u)=\left(A^{1}, \ldots, A^{l}\right)$ is given by

$$
A(u)^{\gamma}(\nabla u, \nabla u)=g^{i j} \Gamma_{\alpha \beta}^{\gamma} \frac{\partial u^{\alpha}}{\partial x_{i}} \frac{\partial u^{\beta}}{\partial x_{j}}
$$

Let $\psi$ be a vector field along $u$, i.e. a section of $u^{-1}(T N)$. In local coordinates

$$
\psi=\psi^{\alpha}(x) \frac{\partial}{\partial u^{\alpha}}
$$

and

$$
\begin{aligned}
d \psi & =\nabla_{\frac{\partial}{\partial x^{i}}}\left(\psi^{\alpha}(x) \frac{\partial}{\partial u^{\alpha}}\right) d x^{i} \\
& =\frac{\partial \psi^{\alpha}}{\partial x^{i}} \frac{\partial}{\partial u^{\alpha}} \otimes d x^{i}+\psi^{\alpha} \Gamma_{\alpha \beta}^{\gamma} \frac{\partial u^{\beta}}{\partial x^{i}} \frac{\partial}{\partial u^{\gamma}} \otimes d x^{i}
\end{aligned}
$$

which is a section of $T^{*} M \otimes u^{-1}(T N)$. Then $\psi$ induces a variation of $u$ by

$$
u_{t}(x)=\exp _{u(x)}(t \psi(x))
$$

We compute

$$
\begin{equation*}
0=\left.\frac{d}{d t} E\left(u_{t}\right)\right|_{t=0}=\int_{M}\langle d u, d \psi\rangle \tag{2}
\end{equation*}
$$

$$
\begin{aligned}
& =\int_{M}\left\langle d u, \nabla_{\frac{\partial}{\partial x^{i}}}\left(\psi^{\alpha}(x) \frac{\partial}{\partial u^{\alpha}}\right) d x^{i}\right\rangle \\
& =-\int_{M}\left\langle\nabla_{\frac{\partial}{\partial x^{i}}} d u, \psi^{\alpha}(x) \frac{\partial}{\partial u^{\alpha}} d x^{i}\right\rangle \\
& =-\int_{M}\langle\operatorname{trace} \nabla d u, \psi\rangle
\end{aligned}
$$

for all $\psi$, where $\nabla$ is the covariant derivatives in $T^{*} M \otimes u^{-1}(T N)$. Note

$$
\nabla_{\frac{\partial}{\partial x^{j}}} d x^{i}=-{ }^{M} \Gamma_{k j}^{i} d x^{k}, \quad \nabla_{\frac{\partial}{\partial u^{\beta}}}\left(\frac{\partial}{\partial u^{\alpha}}\right)={ }^{N} \Gamma_{\alpha \beta}^{\sigma} \frac{\partial}{\partial u^{\sigma}} .
$$

Then we write $\nabla d u=\nabla_{\frac{\partial}{\partial x^{j}}}(d u) d x^{j}$ with

$$
\begin{aligned}
& \nabla_{\frac{\partial}{\partial x^{j}}}(d u)=\nabla_{\frac{\partial}{\partial x^{j}}}\left(\frac{\partial u^{\alpha}}{\partial x^{i}} d x^{i} \otimes \frac{\partial}{\partial u^{\alpha}}\right) \\
& \quad=\frac{\partial^{2} u^{\alpha}}{\partial x^{i} \partial x^{j}} d x^{i} \otimes \frac{\partial}{\partial u^{\alpha}}-{ }^{M} \Gamma_{l j}^{i} \frac{\partial u^{\alpha}}{\partial x^{i}} d x^{l} \otimes \frac{\partial}{\partial u^{\alpha}}+{ }^{N} \Gamma_{\alpha \beta}^{\sigma} \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial u^{\beta}}{\partial x^{j}} d x^{i} \otimes \frac{\partial}{\partial u^{\sigma}} .
\end{aligned}
$$

From the above, we have
Lemma 2.1. The harmonic map equation is

$$
\tau(u):=\operatorname{trace} \nabla d u=0
$$

where $\tau(u)=\tau^{\sigma}(u) \frac{\partial}{\partial u^{\sigma}}$ satisfies

$$
\tau^{\sigma}(u)=g^{i j} \frac{\partial^{2} u^{\sigma}}{\partial x^{i} \partial x^{j}}-g^{i j}{ }^{M} \Gamma_{i j}^{k} \frac{\partial u^{\sigma}}{\partial x^{k}}+g^{i j}{ }^{N} \Gamma_{\alpha \beta}^{\sigma} \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial u^{\beta}}{\partial x^{j}} .
$$

Another way to derive the harmonic map equation:
Let $N \subset \mathbb{R}^{K}$ be an embedded compact manifold in $\mathbb{R}^{K}$. Then there is a $\delta=\delta(N)>0$ such that the nearest point project map $\Pi_{N}: N_{\delta} \rightarrow N$ is smooth, where

$$
N_{\delta}:=\left\{y \in \mathbb{R}^{k}: d(y, N)=\inf _{x \in N}|y-x|<\delta\right\}
$$

and $\Pi_{N}(y) \in N$ is the projection such that $\left|y-\Pi_{N}(y)\right|=d(y, N)$ for $y \in N_{\delta}$. The second result is:

Remark 2.2. A smooth map $u$ from $M$ to $N$ is harmonic if and only if it satisfies

$$
\triangle_{M} u \perp T_{u} N
$$

Proof. Note that $d \Pi_{u}: \mathbb{R}^{k} \rightarrow T_{u} N$ is a tangential projection map for any $u \in N$. For any smooth $\phi \in C_{0}^{\infty}\left(M, \mathbb{R}^{k}\right)$, set

$$
u_{t}=\Pi(u+t \phi)
$$

If $u$ is a critical point of $E$, then we have

$$
\begin{aligned}
\left.\frac{d}{d t}\right|_{t=0} E\left(u_{t}\right) & =\int_{M}\left\langle\nabla u, \nabla\left(d \Pi_{u(x)}(\phi(x))\right)\right\rangle d v_{g} \\
& =-\int_{M}\left\langle\triangle_{M} u, d \Pi_{u(x)}(\phi(x))\right\rangle d v_{g} \\
& =-\int_{M}\left\langle\left(d \Pi_{u(x)}\right)\left(\triangle_{M} u\right), \phi\right\rangle d v_{g}=0
\end{aligned}
$$

In fact, one can show that

$$
\left(d \Pi_{u(x)}\right)\left(\triangle_{M} u\right)=\triangle_{M} u-d^{2} \Pi_{u(x)}(\nabla u, \nabla u)=\triangle_{M} u+A(u)(\nabla u, \nabla u)
$$

## 3. The Heat Flow Approach

In their pioneering paper [7], Eells and Sampson introduced the harmonic map flow to establish existence of harmonic maps for the case that the sectional curvature of the target manifold is non-positive.

In this section, we consider the following evolution problem:

$$
\begin{equation*}
\partial_{t} u=\triangle_{M} u+A(u)(\nabla u, \nabla u) \tag{3}
\end{equation*}
$$

with $u(x, 0)=u_{0}$. We call (3) the heat flow for harmonic maps.
The global estimate is:
Lemma 3.1. If $u(x, t)$ is a solution to the harmonic map flow (3) in $M \times$
$[0, T)$ for some $T$ with $0<T \leq \infty$, we then have

$$
E(u(\cdot, t))+\int_{0}^{t} \int_{M}\left|\partial_{t} u\right|^{2} d v d t=E\left(u_{0}\right)
$$

for any $t \in[0, T)$.
Proof. Taking $\psi=\frac{\partial u}{\partial t}$ in (2), we have

$$
\begin{aligned}
\frac{d}{d t} E(u(\cdot, t)) & =\int_{M}\left\langle\nabla_{\partial_{t}} d u, d u\right\rangle=\int_{M}\left\langle d \frac{\partial u}{\partial t}, d u\right\rangle \\
& =-\int_{M}\left\langle\tau(u), \frac{\partial u}{\partial t}\right\rangle=-\int_{M}\left|\frac{\partial u}{\partial t}\right|^{2}
\end{aligned}
$$

The result follows from integrating by parts.
Let $R^{M}$ and $R^{N}$ be the Riemannian curvature tensors of $M$ and $N$ respectively.

Let $\operatorname{Ric}^{M}$ denote the Ricci curvature of $M$ and $K^{N}$ be the sectional curvature of $N$. Then

Lemma 3.2. Let $u(x, t)$ be a solution to the harmonic map flow in $M \times[0, T]$. Then we have

$$
\begin{aligned}
\left(\partial_{t}-\triangle_{M}\right) e(u)= & -\left|\nabla^{2} u\right|^{2}+\left\langle d u \cdot \operatorname{Ric}^{M}\left(e_{i}\right), d u \cdot e_{i}\right\rangle \\
& -\left\langle R^{N}\left(d u \cdot e_{i}, d u \cdot e_{j}\right) d u \cdot e_{j}, d u \cdot e_{i}\right\rangle
\end{aligned}
$$

where $\left\{e_{i}\right\}$ is an orthonormal frame at $x$ If $K^{N} \leq 0$, then

$$
\left(\partial_{t}-\triangle_{M}\right) e(u) \leq C e(u)
$$

Proof. This original approach is due to Eells-Sampson [7]. Our proof is essentially due to Jost [18].

We introduce normal coordinates at the points $x$ and $u(x)$ such that $g_{i j}(x)=\delta_{i j}$ and $h_{\alpha \beta}(u(x))=\delta_{\alpha \beta}$ and all first derivatives are zero, so the Christoffel symbols vanish at $x$ and $u(x)$. Since $u$ is a solution of the harmonic map flow,

$$
\frac{\partial u^{\sigma}}{\partial t}=g^{i j} \frac{\partial^{2} u^{\sigma}}{\partial x^{i} \partial x^{j}}-g^{i j}{ }^{M} \Gamma_{i j}^{k} \frac{\partial u^{\sigma}}{\partial x^{k}}+g^{i j}{ }^{N} \Gamma_{\alpha \beta}^{\sigma} \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial u^{\beta}}{\partial x^{j}} .
$$

Differentiating this equation at the point $x$ along the direction of $x^{l}$, we have

$$
\begin{aligned}
\frac{\partial^{3} u^{\sigma}}{\partial x^{i} \partial x^{i} \partial x^{l}}= & \frac{\partial u_{x^{l}}^{\sigma}}{\partial t}+\frac{1}{2}\left(g_{i k ; x^{i} x^{l}}+g_{i k ; x^{i} x^{l}}-g_{i i ; x^{k} x^{l}}\right) \frac{\partial u^{\sigma}}{\partial x^{k}} \\
& -\frac{1}{2}\left(h_{\alpha \sigma ; u^{\beta} u^{\gamma}}+h_{\sigma \beta ; u^{\alpha} u^{\gamma}}-h_{\alpha \beta ; u^{\sigma} u^{\gamma}}\right) \frac{\partial u^{\alpha}}{\partial x^{i}} \frac{\partial u^{\beta}}{\partial x^{i}} \frac{\partial u^{\gamma}}{\partial x^{l}}
\end{aligned}
$$

In the coordinates, we have at $x$

$$
g_{; x^{k} x^{k}}^{i j}=-g_{i j ; x^{k} x^{k}}
$$

and by the chain rule

$$
\triangle_{M} h_{\alpha \beta}(u(x))=h_{\alpha \beta ; u^{\sigma} u^{\gamma}} u_{x^{k}}^{\sigma} u_{x^{k}}^{\gamma} .
$$

Combining the above estimate, we have at $x$

$$
\begin{aligned}
& \left(\triangle_{M}-\partial_{t}\right)\left(\frac{1}{2} g^{i j} h_{\alpha \beta} u_{x^{i}}^{\alpha} u_{x^{j}}^{\beta}\right) \\
& =u_{x^{i} x^{k}}^{\alpha} u_{x^{i} x^{k}}^{\alpha}+u_{x^{i}}^{\alpha}\left(u_{x^{i} x^{k} x^{k}}^{\alpha}-\partial_{t} u_{x^{i}}^{\alpha}\right)+\frac{1}{2}\left[g_{; x^{k} x^{k}}^{i j} u_{x^{i}}^{\alpha} u_{x^{j}}^{\alpha}+\triangle_{M} h_{\alpha \beta} u_{x^{i}}^{\alpha} u_{x^{i}}^{\beta}\right] \\
& =|\nabla d u|^{2}-\frac{1}{2}\left(g_{i j ; x^{k} x^{k}}+g_{k k ; x^{i} x^{j}}-g_{k j ; x^{k} x^{i}}-g_{k j ; x^{k} x^{i}}\right) u_{x^{i}}^{\alpha} u_{x^{j}}^{\alpha} \\
& \quad+\frac{1}{2}\left(h_{\alpha \beta ; u^{\sigma} u^{\gamma}}+h_{\sigma \gamma ; u^{\alpha} u^{\beta}}-h_{\alpha \sigma ; u^{\beta} u^{\gamma}}-h_{\beta \sigma ; u^{\alpha} u^{\gamma}}\right) u_{x^{i} i}^{\alpha} u_{x^{i}}^{\beta} u_{x^{k}}^{\sigma} u_{x^{k}}^{\gamma} \\
& =|\nabla d u|^{2}+\frac{1}{2} R_{i j}^{M} u_{x^{i}}^{\alpha} u_{x^{j}}^{\alpha}-\frac{1}{2} R_{\alpha \sigma \beta \gamma}^{N} u_{x^{i}}^{\alpha} u_{x^{i}}^{\beta} u_{x^{k}}^{\sigma} u_{x^{k}}^{\gamma},
\end{aligned}
$$

where at $x$ we noted $R_{i j}^{M}=g^{k l} R_{i k j l}^{M}=R_{i k j k}^{M}$ and

$$
\begin{aligned}
R_{k l i j}^{M} & =\frac{1}{2}\left(g_{j k ; x^{l} x^{i}}+g_{l k ; x^{i} x^{j}}-g_{j l ; x^{k} x^{i}}-g_{i k ; x^{l} x^{j}}-g_{l k ; x^{i} x^{j}}+g_{i l ; x^{k} x^{j}}\right) \\
& =\frac{1}{2}\left(g_{j k ; x^{l} x^{i}}+g_{i l ; x^{k} x^{j}}-g_{j l ; x^{k} x^{i}}-g_{i k ; x^{l} x^{j}}\right) .
\end{aligned}
$$

Since $e_{i}=\frac{\partial}{\partial x_{i}}$ is an orthonormal frame at $x$, we have

$$
\begin{aligned}
\triangle_{M} e(u)-\frac{\partial}{\partial t} e(u)= & |\nabla d u|^{2}+\frac{1}{2}\left\langle d u \cdot \operatorname{Ric}^{M}\left(e_{i}\right), d u \cdot e_{i}\right\rangle \\
& -\frac{1}{2}\left\langle R^{N}\left(d u \cdot e_{i}, d u \cdot e_{j}\right) d u \cdot e_{j}, d u \cdot e_{i}\right\rangle
\end{aligned}
$$

If $K_{N} \leq 0$, we have

$$
\triangle e(u)-\frac{\partial}{\partial t} e(u) \geq-C e(u)
$$

This proves our claim.
The following is the well-know Moser-Harnack estimate:
Lemma 3.3. Let $f \in C^{\infty}\left(B_{R}\left(x_{0}\right) \times\left[t_{0}-R^{2}, t_{0}\right]\right.$ be a nonnegative function satisfying

$$
\left(\partial_{t}-\triangle_{M}\right) f \leq C f
$$

for a constant $C>0$. Then there is a constant $C$ such that

$$
f\left(x_{0}, t_{0}\right) \leq C R^{n+2} \int_{t_{0}-R^{2}}^{t_{0}} \int_{B_{R}\left(x_{0}\right)} f d v_{g} d t
$$

The following theorem is due to Eells-Sampson [7]:
Theorem 3.4. Let $M$ and $N$ be two compact Riemannian manifolds without boundary. Assume that the sectional curvature $K^{N}$ is non-positive. Let $u_{0} \in C^{\infty}(M, N)$ be a given map. Then there is a global smooth solution $u \in C^{\infty}(M \times[0, \infty))$ such that the harmonic map flow with initial value $u_{0}$ has a global smooth solution. As $t \rightarrow \infty$ suitably, $u(\cdot, t)$ converges smoothly to a harmonic map $u_{\infty}$.

Proof. By the local existence, there is a unique smooth solution in $M \times[0, T]$.
Using Lemmas 3.2-3.3, there is a constant $C$ such that $|\nabla u|$ is uniformly bounded in $M \times[0, \infty)$. By the $L^{p}$-estimates, we can show there is a constant $C=C(p, M, N)$ such that

$$
\|u\|_{W^{2, p}\left(B_{R} \times\left(T-R^{2}, T\right)\right)} \leq C(p, M, N)
$$

for some $R>0$. By the bootstrap method, $u$ is smooth in $M \times[0, \infty)$. By the energy inequality, we know

$$
\int_{0}^{\infty} \int_{M}\left|\partial_{t} u\right|^{2} \leq E\left(u_{0}\right)<+\infty
$$

Using the harmonic map heat flow, there is a sequence $t_{k} \rightarrow \infty$ such that $u_{t}\left(\cdot, t_{k}\right) \rightarrow 0$ and $u\left(\cdot, t_{k}\right) \rightarrow u_{\infty}$ smoothly satisfying

$$
\triangle_{M} u_{\infty}+A\left(u_{\infty}\right)\left(\nabla u_{\infty}, \nabla u_{\infty}\right)=0
$$

In fact, $u_{\infty}$ is unique due to Hartman (15].
Lemma 3.5. Let $u(x, t, s)$ be a smooth family of solutions of the harmonic map flow with initial values $u(x, 0, s)=g(x, s)$ for $0 \leq s \leq s_{0}$. Assume again that $N$ has non-positive sectional curvature. For every $s \in\left[0, s_{0}\right]$

$$
\sup _{s \in[0,1]} \sup _{x \in M}\left(h_{\alpha \beta} \frac{\partial u^{\alpha}}{\partial s} \frac{\partial u^{\beta}}{\partial s}\right)
$$

is non-increasing in $t$.
Proof. Using normal coordinates we can obtain

$$
\left(\triangle-\frac{\partial}{\partial t}\right)\left(h_{\alpha \beta} \frac{\partial u^{\alpha}}{\partial s} \frac{\partial u^{\beta}}{\partial s}\right)=h_{\alpha \beta} \frac{\partial^{2} u^{\alpha}}{\partial x^{k} \partial s} \frac{\partial^{2} u^{\beta}}{\partial x^{k} \partial s}-\frac{1}{2} R_{\alpha \beta \sigma \gamma}^{N} u_{s}^{\alpha} u_{x^{k}}^{\beta} u_{s}^{\sigma} u_{x^{k}}^{\gamma} .
$$

Since $K^{N} \leq 0$,

$$
\left(\triangle-\frac{\partial}{\partial t}\right)\left(h_{\alpha \beta} \frac{\partial u^{\alpha}}{\partial s} \frac{\partial u^{\beta}}{\partial s}\right) \geq 0
$$

Then the result follows from the maximum principle for the parabolic equations.

Assume that $u_{1}$ and $u_{2}$ are smooth homotopic maps from $M$ to $N$ and $f: M \times[0,1] \rightarrow N$ is a smooth homotopy with $f(x, 0)=u_{1}(x)$ and $f(x, 1)=$ $u_{2}(x)$. Then the curve $f(x, \cdot)$ is connecting $u_{1}(x)$ and $u_{2}(x)$. Let $g(x, \cdot)$ be the geodesic from $u_{1}(x)$ and $u_{2}(x)$, parameterized by the arc length. We define $\tilde{d}\left(u_{1}(x), u_{2}(x)\right)$ to be the arc length of the geodesic arc. Then

Lemma 3.6. Assume again that $N$ has non-positive sectional curvature. Let $u(x, t, s)$ be a smooth family of solutions of the harmonic map flow with initial values $u(x, 0, s)=g(x, s)$ for $0 \leq s \leq 1$. Then

$$
\sup _{x \in M} \tilde{d}(u(x, t, 0), u(x, t, 1))
$$

is non-increasing in $t \in[0, T]$.

Proof. By the construction, at $t=0$ we have

$$
\sup _{x \in M}\left(h_{\alpha \beta} \frac{\partial u^{\alpha}}{\partial s} \frac{\partial u^{\beta}}{\partial s}\right)=\sup _{x \in M}\left|\frac{\partial g}{\partial s}\right|^{2}=\sup _{x \in M} \tilde{d}^{2}(u(x, 0,0), u(x, 0,1))
$$

For each $t \in[0, T]$,

$$
\tilde{d}^{2}(u(x, t, 0), u(x, t, 1)) \leq \sup _{s \in[0,1]} \sup _{x \in M}\left(h_{\alpha \beta} \frac{\partial u^{\alpha}}{\partial s} \frac{\partial u^{\beta}}{\partial s}\right)
$$

since $u(x, t, \cdot)$ is a curve joining $u(x, t, 0)$ and $u(x, t, 1)$ in the homotopy class. The claim follow from Lemma 3.5.

Let $u_{\infty}$ be the limit of $u\left(x, t_{k}\right)$ as $t_{k} \rightarrow \infty$ and $\tilde{u}_{\infty}$ be the limit of $u\left(x, \tilde{t}_{k}\right)$ as $\tilde{t}_{k} \rightarrow \infty$. By the above Lemmas,

$$
\tilde{d}\left(u\left(x, t_{k}+t\right), u_{\infty}\right) \leq \tilde{d}\left(u\left(x, t_{k}\right), u_{\infty}\right)
$$

By choosing a subsequence $\tilde{t}_{k}$, we show that $u_{\infty}=\tilde{u}_{\infty}$.

## 4. The Sack-Uhlenbeck Functional and Applications

In the two dimensional case, Lemaire 19] and Schoen-Yau [29] established many existence results in each homotopy class under certain topological conditions.

In a well-known paper [26], Sacks and Uhlenbeck established many existence results of minimizing harmonic maps in their homotopy classes by introducing a family of functionals

$$
E_{\alpha}(u)=\int_{M}\left(1+|\nabla u|^{2}\right)^{\alpha} d v
$$

for $\alpha>1$. The $\alpha$-functional $E_{\alpha}$ is now called the 'Sacks-Uhlenbeck functional'. For each $\alpha>1$, there is a minimizer $u_{\alpha}$ of $E_{\alpha}$ in the same homotopy class.

Lemma 4.1. Let $u_{0} \in C^{\infty}(M, N)$ be a given map. For each $\alpha>1$, there is a minimizer $u_{\alpha}$ of $E_{\alpha}$ in the homotopy class $\left[u_{0}\right]$; i.e.

$$
E_{\alpha}\left(u_{\alpha}\right)=\inf \left\{E_{\alpha}(v): v \in W^{1,2 \alpha}(M, N), \quad[v]=\left[u_{0}\right]\right\} .
$$

Moreover, $u_{\alpha}$ satisfies

$$
\begin{equation*}
\triangle_{M} u+(\alpha-1) \frac{\nabla|\nabla u|^{2} \cdot \nabla u}{1+|\nabla u|^{2}}+A(u)(\nabla u, \nabla u)=0 \tag{4}
\end{equation*}
$$

## Proof. Set

$$
m_{\alpha}=\inf \left\{E_{\alpha}(v): v \in W^{1,2 \alpha}(M, N), \quad[v]=\left[u_{0}\right]\right\}
$$

Then $m_{\alpha} \leq E_{\alpha}\left(u_{0}\right) \leq C$ for a uniform constant $C>0$ in $\alpha$. There is a minimizing sequence in $\left[u_{0}\right]$ such that

$$
\int_{M}\left|\nabla u_{i}\right|^{2 \alpha} \leq 1+m_{\alpha} \quad \text { for all } i .
$$

By the lower-semi continuity of $E_{\alpha}$, we have

$$
E_{\alpha}\left(u_{\alpha}\right) \leq \liminf _{i \rightarrow \infty} E_{\alpha}\left(u_{i}\right)=m_{\alpha}
$$

Note that $u_{i}$ converges to $u_{\alpha}$ in $W^{1,2 \alpha}$ weakly and in $C^{\beta}(M, N)$ with $\beta=$ $1-\frac{1}{\alpha}$ by the Sobolev inequality, so $\left[u_{\alpha}\right]=\left[u_{0}\right]$. Therefore, $u_{i} \rightarrow u_{\alpha}$ in $W^{1,2 \alpha}$ strongly. It is easy to check that $u_{\alpha}$ satisfies (4).

The following theorem is due to Sacks-Uhlenbeck 26]:
Theorem 4.2. Let $u_{\alpha}$ be critical points of $E_{\alpha}$ and $E_{\alpha} \leq B$ for some constant $B>0$. As $\alpha \rightarrow 1$, $u_{\alpha}$ weakly sub-converges to a map $u$ in $W^{1,2}(M, N)$. Then there is a finite numbers of points $\left\{x_{1}, \ldots, x_{L}\right\} \subset M$ such that $u_{\alpha}$ converges to $u$ in $C^{\infty}\left(M \backslash\left\{x_{1}, \ldots, x_{L}\right\}, N\right)$. Moreover, $u$ can be extended to a smooth map in $M$.

Moreover, a bubbling phenomenon occurs by studying the limits of the critical points of $E_{\alpha}$ as $\alpha \rightarrow 1$ (see section 4 in [26]).

One of key steps is to derive a Bochner type formula. Let $\left(g_{i j}\right)$ be a Riemannian metric on $M$. Then

Lemma 4.3. (Bochner's type formula) Let $u(x)$ be a smooth solution to the $\alpha$-equation (4) and set $e(u):=|\nabla u|^{2}$. Then, for $\alpha-1$ sufficiently small, we have

$$
\begin{equation*}
\left(g^{i j}+\frac{(\alpha-1)}{1+|\nabla u|^{2}} g^{i k} \frac{\partial u^{\beta}}{\partial x_{k}} g^{j l} \frac{\partial u^{\beta}}{\partial x_{l}}\right) \frac{\partial^{2} e(u)}{\partial x_{i} \partial x_{j}} \geq-C e(u)(e(u)+1) \tag{5}
\end{equation*}
$$

where the constant $C$ does not depend on $\alpha$ and $u$.
Proof. In a neighborhood of each point $x \in M$, we can choose an orthonormal frame $\left\{e_{1}, e_{2}\right\}$. We denote by $\nabla_{i}$ the first covariant derivative with respect to $e_{i}$ and by $u_{j i}$ the second covariant derivatives of $u$ and so on. In a local frame, we have

$$
\nabla_{j} e(u)=2 u_{k}^{\gamma} u_{k j}^{\gamma}, \quad\left|\nabla^{2} u\right|^{2}=\sum_{k, i, \gamma}\left|u_{k i}^{\gamma}\right|^{2}
$$

The Ricci identity is

$$
u_{i k i}=u_{i i k}+R_{i k} u_{i}
$$

where $R_{i k}$ is the Ricci curvature. Then we have

$$
\begin{aligned}
& \nabla_{i}\left(\left(\delta_{i j}+2(\alpha-1) \frac{u_{i}^{\beta} u_{j}^{\beta}}{1+|\nabla u|^{2}}\right) \nabla_{j} e(u)\right) \\
& \quad=2 \nabla_{i}\left(u_{k}^{\gamma} u_{k i}^{\gamma}+2(\alpha-1) \frac{u_{i}^{\beta} u_{j}^{\beta} u_{k}^{\gamma} u_{k j}^{\gamma}}{1+|\nabla u|^{2}}\right) \\
& \quad=2\left|\nabla^{2} u\right|^{2}+2 u_{k}^{\gamma} u_{i i k}^{\gamma}+4(\alpha-1) \nabla_{k}\left(\frac{u_{k}^{\gamma} u_{j}^{\gamma} u_{i}^{\beta} u_{i j}^{\beta}}{1+|\nabla u|^{2}}\right) \\
& \quad \geq\left|\nabla^{2} u\right|^{2}+2 u_{k}^{\gamma} \nabla_{k}\left(u_{i i}^{\gamma}+2(\alpha-1) \frac{u_{j}^{\gamma} u_{i}^{\beta} u_{i j}^{\beta}}{1+|\nabla u|^{2}}\right)-C e(u)
\end{aligned}
$$

for $\alpha-1$ sufficiently small, where we used the Ricci identity twice for switching third order derivatives. Using the $\alpha$-equation (41) and the Young's inequality, we have

$$
-\left(\delta_{i j}+2(\alpha-1) \frac{u_{i}^{\beta} u_{j}^{\beta}}{1+|\nabla u|^{2}}\right) \nabla_{i j}^{2} e(u)
$$

$$
\begin{aligned}
& \leq-\frac{1}{2}\left|\nabla^{2} u\right|^{2}-2 u_{k}^{\gamma} \nabla_{k}\left(A^{\gamma}(u)(\nabla u, \nabla u)\right)+C e(u) \\
& \leq C e(u)(e(u)+1)
\end{aligned}
$$

for $\alpha-1$ sufficiently small. This proves our claim.
The following local Harnack inequality is taken from Theorem 9.20 of Gilberg-Trudinger's book 13].

Lemma 4.4. Let $v(x) \in W^{2, n}(\Omega)$ and let

$$
a_{i j} D_{i j} v+C v \geq 0
$$

where $a_{i j}$ are measurable functions in $\Omega \subset \mathbb{R}^{n}$ satisfying

$$
\lambda|\xi|^{2} \leq a^{i j}(x) \xi_{i} \xi_{j} \leq \Lambda|\xi|^{2}
$$

for any two positive constants $\lambda$ and $\Lambda$. Then for any $p>0$ and $R>0$ with $B_{R}(x) \subset \Omega$, we have

$$
|v(x)| \leq C\left(\frac{1}{R^{n}} \int_{B_{R}(x)}\left(v^{+}\right)^{p}\right)^{1 / p}
$$

Remark. Moser [23] proved the inequality for $p>1$ and Trudinger 34] proved the inequality for all $p>0$. In fact, we need the case for $p=1$.

The following $\varepsilon$-regularity estimate is essentially due to Schoen in [27]:
Lemma 4.5. Let $u(x)$ be a solution of the $\alpha$-equation (4). There is a small constant $\varepsilon_{0}>0$ such that if

$$
\int_{B_{R}}|\nabla u(x)|^{2} d x \leq \varepsilon_{0}
$$

for a ball $B_{R}$ with some $R>0$, then

$$
|\nabla u(x)|^{2} \leq \frac{C}{R^{2}} \int_{B_{R}}|\nabla u|^{2} d v_{g} \quad \forall x \in B_{R / 2}
$$

where the constant $C$ depends not on $x$ and $\alpha$.

Proof. We choose $\sigma_{0} \in[0, R]$ such that

$$
\left(R-\sigma_{0}\right)^{2} \sup _{B_{\sigma_{0}}} e(u)=\max _{\sigma \in[0, R]}\left\{(R-\sigma)^{2} \sup _{B_{\sigma}} e(u)\right\}
$$

Let $x_{0}$ be the point in $\bar{B}_{\sigma_{0}}$ such that

$$
e_{0}=: e(u)\left(x_{0}\right)=\sup _{B_{\sigma_{0}}} e(u)
$$

Set $\rho_{0}=\frac{1}{2}\left(R-\sigma_{0}\right)$, which implies $R-\left(\sigma_{0}+\rho_{0}\right)=\rho_{0}$. Then

$$
\sup _{B_{\rho_{0}}\left(x_{0}\right)} e(u) \leq \sup _{B_{\sigma_{0}+\rho_{0}}} e(u) \leq 4 e_{0}
$$

We claim

$$
r_{0}=\left(e_{0}\right)^{1 / 2} \rho_{0} \leq 1
$$

Otherwise, we may assume that $r_{0}>1$; i.e. $e_{0}\left(R-\sigma_{0}\right)^{2}>4$. We define a new map $v \in C^{2}\left(B_{r_{0}}\left(x_{0}\right)\right)$ by

$$
v(x)=u\left(x_{0}+\frac{x}{e_{0}^{1 / 2}}\right)
$$

for $x \in B_{r_{0}}(0)$. Then $v$ satisfies the scaled $\alpha$-equation

$$
\frac{\operatorname{div}\left(\left(e_{0}^{-1}+|\nabla v|^{2}\right)^{\alpha-1} \nabla v\right)}{\left(e_{0}^{-1}+|\nabla v|^{2}\right)^{\alpha-1}}+A(v)(\nabla v, \nabla v)=0
$$

and

$$
\begin{equation*}
e(v)(0)=1, \quad \sup _{B_{r_{0}}} e(v) \leq 4 \tag{6}
\end{equation*}
$$

By Lemma 4.3 and (6), we have

$$
-a_{i j}(v) \nabla_{i j}^{2} e(v) \leq C e(v)
$$

where

$$
a_{i j}(v)=\delta_{i j}+2(\alpha-1) \frac{v_{i}^{\beta} v_{j}^{\beta}}{e_{0}^{-1}+|\nabla v|^{2}} .
$$

The symmetric matrix $\left(a_{i j}(v)\right)$ has positive eigenvalues satisfying the uniform elliptic condition. By the Moser-Trudinger estimate (Lemma 4.4), we
have

$$
1=e(v)(0) \leq C \int_{B_{1}(0)} e(v) \leq C \varepsilon_{0}
$$

which is impossible if we choose $\varepsilon_{0}$ small, where we note

$$
\begin{equation*}
\int_{B_{r_{0}}(0)} e(v)=\int_{B_{\rho_{0}\left(x_{0}\right)}} e(u) \leq \varepsilon_{0} \tag{7}
\end{equation*}
$$

This proves that $r_{0} \leq 1$.
Using the Moser-Trudinger estimate again, we have

$$
1=e(v)(0) \leq C r_{0}^{-2} \int_{B_{r_{0}}} e(v)=C \frac{1}{e_{0} \rho_{0}^{2}} \int_{B_{\rho_{0}\left(x_{0}\right)}} e(u)
$$

which implies

$$
\left(\frac{R}{2}\right)^{2}|\nabla u(x)|^{2} \leq 4 e_{0} \rho_{0}^{2} \leq C \int_{B_{R}}|\nabla u|^{2} d v_{g} \quad \forall x \in B_{R / 2}
$$

Using above two Lemmas, We prove Theorem 4.2;
Proof. We can see that there is a constant $C$ such that

$$
\int_{M}\left|\nabla u_{\alpha}\right|^{2} \leq C
$$

Then there are finite singular points of the set

$$
\Sigma=\left\{x_{1}, \cdots, x_{l}\right\}
$$

such that for every point $x_{0} \in M \backslash \Sigma$, there is $r_{0}>0$ satisfying

$$
\int_{B_{r_{0}\left(x_{0}\right)}}\left|\nabla u_{\alpha}\right|^{2} \leq \varepsilon_{0}
$$

By Lemma 4.5, we have

$$
\left\|u_{\alpha}\right\|_{C^{k}\left(B_{r_{0} / 2}\left(x_{0}\right)\right)} \leq C\left(k, x_{0}\right), \quad \forall k \geq 1
$$

Then there exists a subsequence such that $u_{\alpha_{i}} \rightarrow u$ in $C_{\text {loc }}^{k}(M \backslash \Sigma, N)$ for all $k \geq 1$ and $u \in C^{\infty}(M \backslash \Sigma, N)$ is harmonic map. By the removable singularity
theorem (see 26] and also below Theorem 4.8), $u \in C^{\infty}(M, N)$.
Theorem 4.6. If $\operatorname{dim}(M)=2$ and $\pi_{2}(N)=\emptyset$, then any smooth map $u_{0}$ is homotopic to a smooth harmonic map.

Proof.Let $u_{i}=u_{\alpha_{i}}$ be the above minimizers of $E_{\alpha_{i}}$ in the same homotopy class $\left[u_{0}\right]$. Using Theorem 4.2, there exist finitely many points $x_{1}, \ldots, x_{l}$ such that $u_{i}$ converges to $u$ smoothly in $M$ away from these points. By the well-known removable singularity theorem on harmonic maps (see below), $u$ can be extended to a smooth map on $M$.

Without loss of generality, we assume that $l=1$. Let $\eta(r)$ be a smooth cutoff function in $\mathbb{R}$ with the property that $\eta \equiv 1$ for $r \geq 1$ and $\eta \equiv 0$ for $r \leq 1 / 2$. For some $\rho>0$, we define a new sequence of maps $v_{i}: M \rightarrow N$ such that $v_{i}$ is the same as $u_{i}$ outside $B_{\rho}\left(x_{1}\right)$, and for $x \in B_{\rho}\left(x_{1}\right)$,

$$
v_{i}(x)=\exp _{u(x)}\left(\eta\left(\frac{|x|}{\rho}\right) \exp _{u(x)}^{-1} \circ u_{i}(x)\right),
$$

where exp is the exponential map on $N$.
We claim that

$$
\begin{equation*}
\left\|v_{i}-u\right\|_{W^{1,2}(M)} \rightarrow 0 \tag{8}
\end{equation*}
$$

as $i \rightarrow \infty$.
To see this, it suffices to consider $B_{\rho}\left(x_{1}\right) \backslash B_{\rho / 2}\left(x_{1}\right)$ because $v_{i} \equiv u$ on $B_{\rho / 2}\left(x_{1}\right)$ and $v_{i} \equiv u_{i}$ outside $B_{\rho}\left(x_{1}\right)$. On the other hand, $u_{i}$ converges to $u$ on $B_{\rho}\left(x_{1}\right) \backslash B_{\rho / 2}\left(x_{1}\right)$ strongly in $W^{1,2}$ and $C^{\beta}$ for some $\beta>0$. Hence for large $i, v_{i}\left(B_{\rho\left(x_{1}\right)} \backslash B_{\rho / 2}\left(x_{1}\right)\right)$ lies in a small neighborhood of $u\left(x_{1}\right)$, where $\exp _{u(x)}^{-1}$ is a well defined smooth map (if $\rho$ is small). Since $F(y)=\exp _{u(x)}\left(\eta\left(\frac{|x|}{\rho}\right) \exp _{u(x)}^{-1} y\right)$ is a smooth map from a neighborhood of $u\left(x_{1}\right)$ into itself, we have

$$
\begin{aligned}
\sup _{B_{\rho} \backslash B_{\rho / 2}\left(x_{1}\right)}\left|\nabla\left(v_{i}-u\right)\right| & =\sup _{B_{\rho} \backslash B_{\rho / 2}\left(x_{1}\right)}\left|\nabla\left(F \circ u_{i}-F \circ u\right)\right| \\
& \leq C \sup _{B_{\rho} \backslash B_{\rho / 2}\left(x_{1}\right)}\left|\nabla\left(u_{i}-u\right)\right| \rightarrow 0 \quad \text { as } i \rightarrow \infty .
\end{aligned}
$$

The claim (8) is proved.

Since $\pi_{2}(N)$ is trivial, $v_{i}$ is in the same homotopy class as $u_{i}$. Since $u_{i}$ is a minimizer of $E_{\alpha_{i}}$ and $u_{i}$ converges weakly to $u$ in $W^{1,2}$, we have

$$
\begin{aligned}
E(u)+|M| & \leq \liminf _{i \rightarrow \infty} E\left(u_{i}\right)+|M| \\
& \leq \limsup _{i \rightarrow \infty} E_{\alpha_{i}}\left(u_{i}\right) \leq \limsup _{i \rightarrow \infty} E_{\alpha_{i}}\left(v_{i}\right) \\
& =E(u)+|M|,
\end{aligned}
$$

which implies

$$
E(u)=\lim _{i \rightarrow \infty} E\left(u_{i}\right)
$$

Now, $u_{i}$ converges to $u$ strongly in $W^{1,2}(M, N)$, which means that there is no energy concentration, and Theorem 4.2 in turn shows that the convergence is in $C^{\beta}$ for some $\beta>0$ and hence also in $C^{\infty}(M, N)$.

In order to establish the removable singularity theorem of Sack-Uhlenbeck [26], we need

Lemma 4.7. Let $u \in C^{\infty}(\bar{B} \backslash\{0\}, N)$ be a smooth harmonic map with $E(u ; B) \leq+\infty$, where $B=B_{1}$. Then for any $0<r \leq 1$,

$$
\int_{0}^{2 \pi}\left|\frac{\partial u}{\partial r}\right|^{2}(r, \theta) d \theta=r^{-2} \int_{0}^{2 \pi}\left|\frac{\partial u}{\partial \theta}\right|^{2}(r, \theta) d \theta
$$

Proof. The result is a consequence of the Pohozaev identity (see [22]). However, 0 is a singular point. We need to use a test function to cut off the singularity. For a very small $\varepsilon>0$, let $\phi(x)=\phi_{\varepsilon}(r) \in C^{\infty}(B)$ with $r=|x|$ be a cut-off function such that $\phi=0$ in $B_{\varepsilon}$ and $\phi=1$ in $B \backslash B_{2 \varepsilon}, 0 \leq \phi \leq 1$ and $|\nabla \phi| \leq 2 / \varepsilon$.

Multiplying the harmonic map equation by $\phi x \cdot \nabla u$ and then integrating by parts, we have

$$
\begin{aligned}
0 & =\int_{B} \triangle u \cdot(\phi x \cdot \nabla u) d x \\
& =\int_{\partial B}\left(\left|\partial_{r} u\right|^{2}-\frac{1}{2}|\nabla u|^{2}\right) d \theta+\int_{B}|x| \phi^{\prime}(|x|)\left(\frac{1}{2}|\nabla u|^{2}-\left|\partial_{r} u\right|^{2}\right) d x .
\end{aligned}
$$

Since $E(u ; B)$ is finite, the claim follows from taking $\varepsilon \rightarrow 0$ in the above identity.

Theorem 4.8. If $u \in C^{\infty}(\bar{B} \backslash\{0\}) \rightarrow N$ is a harmonic map and $E(u ; B)<$ $+\infty$, then $u \in C^{\infty}(B, N)$.

Proof. This proof is due to Sack-Uhlenbeck in [26]. Since $E$ is conformal invariant, we assume that $\int_{B_{2}}|\nabla u|^{2} \leq \varepsilon_{0}^{2}$, where $\varepsilon_{0}$ is a small constant. For any nonzero point $x \in B$, we have $E\left(u, B_{|x|}\right) \leq \varepsilon_{0}^{2}$. Then Lemma 4.5 (with $\alpha=1$ ) yields

$$
|x||\nabla u|(x) \leq C\|\nabla u\|_{L^{2}(B)} \leq C \varepsilon_{0}
$$

For any integer $m \geq 1$, set

$$
A_{m}=\left\{x \in B: 2^{-m} \leq|x| \leq 2^{-m+1}\right\}
$$

There exists a radial symmetric harmonic function $q(x)=q(r)$ in $A_{m}$ to solve the harmonic equation

$$
\triangle q=0 \quad \text { in } A_{m}
$$

with boundary conditions $q\left(2^{-m}\right)=\frac{1}{2 \pi} \int_{0}^{2 \pi} u\left(2^{-m}, \theta\right) d \theta$ and $q\left(2^{-m+1}\right)=$ $\frac{1}{2 \pi} \int_{0}^{2 \pi} u\left(2^{-m+1}, \theta\right) d \theta$. By the maximum principle, we have

$$
\begin{aligned}
|q(x)-u(x)| & =|q(r)-u(r, \theta)| \leq 2 \max _{x, y \in A_{m}}\{|u(x)-u(y)|\} \\
& \leq 2^{-m+3} \max _{x \in A_{m}}|\nabla u(x)| \leq C\left(\int_{|x| \leq 2^{-m+2}}|\nabla u|^{2}\right)^{1 / 2} \leq C \varepsilon_{0} .
\end{aligned}
$$

Multiplying the harmonic map equation by $u-q$ and then integrating by parts yields that

$$
\begin{aligned}
& \int_{B}|\nabla(q(x)-u(x))|^{2}=\sum_{m=1}^{\infty} \int_{A_{m}}|\nabla(q(x)-u(x))|^{2} \\
& =\left.\sum_{m=1}^{\infty} r \int_{0}^{2 \pi}(q(r)-u(r, \theta)) \cdot\left(u_{r}(r, \theta)-q^{\prime}(r)\right) d \theta\right|_{r=2^{-m}} ^{r=2^{-m+1}}+\int_{B} \Delta u \cdot(u-q) .
\end{aligned}
$$

Note for any $m \geq 1$

$$
\left.\int_{0}^{2 \pi}(q(r)-u(r, \theta)) \cdot q^{\prime}(r) d \theta\right|_{r=2^{-m}}
$$

$$
=\left(q\left(2^{-m}\right) 2 \pi-\int_{0}^{2 \pi} u\left(2^{-m}, \theta\right) d \theta\right) \cdot q^{\prime}(r)=0
$$

Since $u, q$ and $u_{r}$ are continuous, the boundary terms with $u_{r}$ cancel for any finite $m$; i.e.

$$
\begin{aligned}
& \left.\sum_{m=1}^{\infty} r \int_{0}^{2 \pi}(q(r)-u(r, \theta)) \cdot u_{r}(r, \theta) d \theta\right|_{r=2^{-m}} ^{r=2^{-m+1}} \\
& =\int_{0}^{2 \pi}(q(1)-u(1, \theta)) \cdot u_{r}(1, \theta) d \theta \\
& -\lim _{m \rightarrow \infty} 2^{-m} \int_{0}^{2 \pi}\left(q\left(2^{-m}\right)-u\left(2^{-m}, \theta\right)\right) \cdot u_{r}\left(2^{-m}, \theta\right) d \theta \\
& =\int_{0}^{2 \pi}(q(1)-u(1, \theta)) \cdot u_{r}(1, \theta) d \theta
\end{aligned}
$$

Since $|A(u)(\nabla u, \nabla u)| \leq C|\nabla u|^{2}$, we have

$$
\left|\int_{B} \triangle u \cdot(u-q)\right| \leq C\|u-q\|_{L^{\infty}(B)} \int_{B}|\nabla u|^{2} d x \leq C \varepsilon_{0}\|\nabla u\|_{L^{2}(B)}^{2} .
$$

Therefore

$$
\begin{aligned}
\int_{B}|\nabla(u-q)|^{2} \leq & \left(\int_{0}^{2 \pi}|q(1)-u(1, \theta)|^{2} d \theta\right)^{1 / 2}\left(\int_{0}^{2 \pi}\left|u_{r}(1, \theta)\right|^{2} d \theta\right)^{1 / 2} \\
& +C \varepsilon_{0}\|\nabla u\|_{L^{2}(B)}^{2}
\end{aligned}
$$

Since $q$ does not depend on $\theta$, it follows from Lemma 4.7 that

$$
\frac{1}{2} \int_{B}|\nabla u|^{2}=\frac{1}{2} \int_{0}^{1} \int_{0}^{2 \pi}\left|u_{r}\right|^{2}+\frac{1}{r^{2}}\left|u_{\theta}\right|^{2} d \theta r d r \leq \int_{B}|\nabla(u-q)|^{2} .
$$

By the Poincare inequality on $S^{1}$, we have

$$
\int_{r=1}|u-q|^{2} d \theta \leq \int_{r=1}\left|u_{\theta}\right|^{2} d \theta=\frac{1}{2} \int_{r=1}|\nabla u|^{2} d \theta
$$

Choosing $\varepsilon_{0}$ sufficiently small with $\delta_{0}=C \varepsilon_{0}<1$, we obtain

$$
\left(1-\delta_{0}\right) \int_{B}|\nabla u|^{2} \leq \int_{\partial B}|\nabla u|^{2} .
$$

By scaling in $r$, we can obtain

$$
\left(1-\delta_{0}\right) \int_{B_{r}}|\nabla u|^{2} \leq r \int_{\partial B_{r}}|\nabla u|^{2}=r \frac{d}{d r}\left(\int_{B_{r}}|\nabla u|^{2}\right)
$$

for all $r$ with $0<r \leq 1$. This implies

$$
\int_{B_{r}}|\nabla u|^{2} \leq r^{1-\delta_{0}} \int_{B}|\nabla u|^{2}
$$

Using the $\varepsilon$-regularity, we have

$$
|x|^{2}|\nabla u|^{2}(x) \leq C \int_{B_{2|x|}}|\nabla u|^{2} \leq C|x|^{1-\delta_{0}} \int_{B}|\nabla u|^{2}, \quad \forall 0<r<\frac{1}{2}
$$

This implies $\nabla u \in L^{p}(B)$ for some $p>2$ and $u \in C^{\alpha}(B)$ for some $0<\alpha<1$. By using the elliptic theory of partial differential equations, $u \in C^{\infty}(B, N)$.

In fact, we can improve the above result as follows. Let $u_{i}$ be a sequence of smooth maps minimizing $E(u)=\int_{M}|\nabla u|^{2} d v$ in a fixed homotopy class of maps. Since $u_{i}$ is bounded in $W^{1,2}$, there is a weak limit $u$ in $W^{1,2}(M, N)$. In general, $u$ may not be in the same homotopy class, but we can show:

Remark 4.9. Let $u$ be the weak limit of the above minimizing sequence $\left\{u_{i}\right\}$. Then it is a harmonic map from $M$ to $N$ and there exist harmonic maps $\omega_{k}: S^{2} \rightarrow N$ with $k=1, \ldots, l$ such that

$$
\begin{equation*}
\lim _{i \rightarrow \infty} E\left(u_{i}\right)=E(u)+\sum_{k=1}^{l} E\left(\omega_{k}\right) \tag{9}
\end{equation*}
$$

Moreover, if $\pi_{2}(N)$ is trivial, then $u_{i}$ converges strongly to $u$ in $W^{1,2}(M, N)$ and $u$ is a minimizer in the homotopy class of $u_{i}$. (see [17], also [22]).

## 5. The Partial Regularity of Minimizing Harmonic Maps

The study of partial regularity of various classes of weakly harmonic maps has been of great interest for a number of years. Schoen-Uhlenbeck [28] and Giaquinta-Giusti [10] established that an energy minimizing map $u: M \rightarrow N$ between Riemannian manifolds is smooth in $M$ away from a singular set $\Sigma$ that has Hausdorff dimension $\leq n-3$, where $n$ is the dimension
of $M$. Bethuel [1] proved that a weak stationary harmonic map $u: M \rightarrow N$ is smooth away from a singular set of vanishing ( $n-2$ )-dimensional Hausdorff measure. Lin [L] proved an important result that if there is no non-constant harmonic map from $S^{2}$ to $N$, then the singular set of any stationary harmonic map into $N$ has to be $(n-4)$-rectifiable.

Let $n$ and $k$ be positive integers with $n \geq 3$. Let $\Omega$ be a bounded smooth domain in $n$-dimensional space $\mathbb{R}^{n}$ and let $N \subset \mathbb{R}^{l}$ be a compact $k$-dimensional Riemannian manifold without boundary for some integer $l$.

For a map $u \in W^{1,2}(\Omega, N):=\left\{v \in W^{1,2}\left(\Omega, \mathbb{R}^{l}\right) \mid v \in N\right\}$, its Dirichlet energy is given by

$$
E(u, \Omega)=\int_{\Omega}|\nabla u|^{2} d x
$$

where $\nabla u$ is the gradient of $u$.
A map $u \in W^{1,2}(\Omega, N)$ is said to be a (weakly) harmonic map if $u$ belongs to $W^{1,2}(\Omega, N)$ and satisfies

$$
\int_{\Omega}\langle\nabla u, \nabla \phi\rangle+A(u)(\nabla u, \nabla u) \cdot \phi d v_{g}=0
$$

for all $\phi \in C^{\infty}\left(\Omega, \mathbb{R}^{l}\right)$.
Without any assumption on weak harmonic maps, Rivière in 24] gave an counterexample that weakly harmonic maps may have singularities. In this section, we will prove partial regularity of the classic result of minimizing harmonic maps by Schoen-Uhlenbeck.

Definition 5.1. For $0 \leq s \leq n$, the $s$-dimensional Hausdorff measure $\mathcal{H}^{s}$ on $\mathbb{R}^{n}$ is defined by

$$
\mathcal{H}^{s}(A)=\lim _{\delta \rightarrow 0^{+}} \mathcal{H}_{\delta}^{s}(A), \quad A \subset \mathbb{R}^{n}
$$

with

$$
\mathcal{H}_{\delta}^{s}(A)=\inf \left\{\sum_{i} r_{i}^{s}: A \subset \bigcup_{i} B_{r_{i}}, r_{i} \leq \delta\right\}
$$

The Hausdorff dimension of $A \subset \mathbb{R}^{n}$ is defined by

$$
\operatorname{dim}_{\mathcal{H}}(A):=\inf \left\{s: \mathcal{H}^{s}(A)=0\right\}=\sup \left\{s: \mathcal{H}^{t}(A)=\infty\right\}
$$

The main result of this section is:
Theorem 5.2. Let $u \in W^{1,2}(\Omega ; N)$ be a minimizer of $E(u)$ in $W^{1,2}(\Omega ; N)$. Then, $u$ is smooth in $M \backslash \Sigma$, where $\Sigma$ is the singular set of $u$ and is defined by

$$
\Sigma:=\{x \in \Omega: u \text { is discontinuous at } x .\}
$$

Moreover, the Hausdorff dimension of $\Sigma$ is less or equal to $n-3$.
Lemma 5.3 (Monotonicity). For $n \geq 3$, let $u \in W^{1,2}(\Omega, N)$ be a minimizing harmonic map. Then for any $x_{0} \in \Omega$ and for any two $r$ and $R$, we have

$$
\begin{equation*}
R^{2-n} \int_{B_{R}\left(x_{0}\right)}|\nabla u|^{2}-s^{2-n} \int_{B_{s}\left(x_{0}\right)}|\nabla u|^{2} \geq \int_{B_{R}\left(x_{0}\right) \backslash B_{s}\left(x_{0}\right)} r^{2-n}\left|\frac{\partial u}{\partial r}\right|^{2} \tag{10}
\end{equation*}
$$

with $r=\left|x-x_{0}\right|$.

Proof. The hint is to use that $u_{r}(x)=u\left(\frac{r x}{|x|}\right)$ for $x \in B_{r}$ with $r>0$. Using the minimality of $u$, we have

$$
\int_{B_{r}}|\nabla u|^{2} \leq \int_{B_{r}}\left|\nabla u_{r}\right|^{2}=\frac{r}{n-2} \int_{\partial B_{r}}\left(|\nabla u|^{2}-\left|\frac{\partial u}{\partial r}\right|^{2}\right) d \mathcal{H}^{n-1} .
$$

We omit all details. (see [28]).
In fact, the inequality also holds for stationary harmonic maps.

Assume that $u: B_{1} \rightarrow N$ is a minimizing harmonic map satisfying

$$
E\left(u ; B_{1}\right)=\int_{B_{1}}|\nabla u|^{2} d v_{g} \leq \varepsilon
$$

Let $\phi \in C^{\infty}\left(\mathbb{R}^{n}, \mathbb{R}^{+}\right)$be a radial mollifying function so that supp $\phi \subset B_{1}$ and $\int_{\mathbb{R}^{n}} \phi=1$ (see Chapter 7 of the book of Gilberg-Trudinger [13]).

Let $h \in\left(0, \frac{1}{4}\right]$, set

$$
u^{h}(x)=\int_{B_{1}} \phi^{h}(x-y) u(y) d y, \quad \forall x \in B_{1 / 2}
$$

where $\phi^{h}(x)=h^{-n} \phi\left(\frac{x}{h}\right)$. Then

$$
\operatorname{dist}^{2}\left(u^{h}(x), N\right) \leq \frac{1}{\left|B_{h}\right|} \int_{B_{h}}\left|u(y)-u^{h}(x)\right|^{2} d y \leq C h^{2-n} \int_{B_{h}}|\nabla u(y)|^{2} d y \leq C \varepsilon
$$

where we used a variant of Poincare's inequality

$$
\int_{B_{1}}\left|u(x)-\int_{B_{1}} \phi(y) u(y) d y\right|^{2} d x \leq C \int_{B_{1}}|\nabla u|^{2}
$$

For a sufficiently small, $u^{\bar{h}}\left(B_{1 / 2}\right) \subset N_{\delta_{0}}$ and we can define

$$
u_{\bar{h}}:=\Pi_{N}\left(u^{\bar{h}}\right): B_{1 / 2} \rightarrow N .
$$

Lemma 5.4. For $\bar{h}=\varepsilon^{1 / 4}$, we have

$$
\begin{align*}
\int_{B_{1 / 2}}\left|\nabla u^{\bar{h}}\right|^{2} & \leq C \int_{B_{1}}|\nabla u|^{2},  \tag{11}\\
\sup _{x \in B_{1 / 2}}\left|u^{\bar{h}}(x)-u^{\bar{h}}(0)\right|^{2} & \leq C \varepsilon^{1 / 2} \tag{12}
\end{align*}
$$

where the constant $C$ does not depend on $\alpha$ and $u$.

Proof. For any $x \in B_{1 / 2}$, we have

$$
\begin{aligned}
\left|\nabla u^{\bar{h}}\right|^{2}(x) & =\left|\int_{B_{1}} \phi^{\bar{h}}(x-y) \nabla u(y) d y\right|^{2} \\
& \leq \int_{B_{1}} \phi^{\bar{h}}(x-y)|\nabla u(y)|^{2} d y \\
& \leq C \frac{1}{\bar{h}^{n}} \int_{B_{\bar{h}}(x)}|\nabla u(y)|^{2} d y \leq C \frac{\varepsilon}{\bar{h}^{2}}=C \varepsilon^{1 / 2} .
\end{aligned}
$$

The inequality (12) also follows.

Let $\bar{h}=\varepsilon^{1 / 4}, \tau=\varepsilon^{1 / 8}$. We choose $h(x)=h(r), r=|x|$ to be a nonincreasing smooth function of $r$ such that

$$
h(x)=h(r)=\bar{h}, \text { for } r \leq \theta, \quad h(\theta+\tau)=0, \quad\left|h^{\prime}(r)\right| \leq 2 \varepsilon^{1 / 8} .
$$

Then we set

$$
u^{h(x)}(x)=\int_{B_{1}} \phi^{h(x)}(x-y) u(y) d y
$$

We know

$$
u_{h(x)}:=\Pi \circ u^{h(x)}(x) \in N .
$$

Then we have

Lemma 5.5. For $\theta \in\left(\tau, \frac{1}{4}\right]$, the above map $u_{h(x)}$ satisfies $u_{h}=u$ on $B_{1 / 2} \backslash B_{\theta+\tau}$ and

$$
\int_{B_{\theta+\tau} \backslash B_{\theta}}\left|\nabla u_{h}\right|^{2} d x \leq C \int_{B_{\theta+2 \tau} \backslash B_{\theta-\tau}}|\nabla u|^{2} d x
$$

where the constant $C$ does not depend on $\theta$ and $u$.

Proof. Since $\Pi$ is smooth, it suffices to prove this lemma for $u^{h}$ instead of $u_{h}$. Note that

$$
u^{h}=\int_{B_{1}} \phi(y) u(x-h(x) y) d y .
$$

We compute

$$
\frac{\partial u^{h}}{\partial x^{\alpha}}=\int_{B_{1}} \phi(y)\left[\frac{\partial u}{\partial x^{\alpha}}(x-h y)-\frac{\partial h}{\partial x^{\alpha}} \cdot \nabla u(x-h y)\right] d y
$$

Then

$$
\begin{aligned}
\int_{B_{\theta+\tau} \backslash B_{\theta}}\left|\nabla u^{h}\right|^{2} & \leq C \int_{B_{\theta+\tau} \backslash B_{\theta}} \int_{B_{1}} \phi(y)|\nabla u|^{2}(x-h y) d y d x \\
& \leq C \int_{B_{\theta+2 \tau} \backslash B_{\theta-\tau}}|\nabla u|^{2} d x
\end{aligned}
$$

Lemma 5.6. (Energy decay estimate) For $n \geq 3$, there are a small constant $\varepsilon=\varepsilon(n, M)$ and another constant $\theta \in\left(0, \frac{1}{4}\right)$ such that if $u: B_{1} \rightarrow N$ is a minimizing harmonic map satisfying

$$
E\left(u ; B_{1}\right)=\int_{B_{1}}|\nabla u|^{2} d v_{g} \leq \varepsilon
$$

then

$$
\begin{equation*}
\theta^{2-n} \int_{B_{\theta}}|\nabla u|^{2} \leq \frac{1}{2} \int_{B_{1}}|\nabla u|^{2} \tag{13}
\end{equation*}
$$

Proof. The proof is divided into three parts.
Claim 1: For any $\theta \in\left(0, \frac{1}{4}\right]$,

$$
\begin{equation*}
\theta^{2-n} \int_{B_{\theta}}\left|\nabla u_{\bar{h}}\right|^{2} \leq C\left(\theta^{2-n} \varepsilon^{1 / 4}+\theta^{2}\right) \int_{B_{1}}|\nabla u|^{2} \tag{14}
\end{equation*}
$$

Claim 2: There is a $\theta \in[\bar{\theta}, 2 \bar{\theta}]$ with $\bar{\theta}=\varepsilon^{\gamma_{n}}$ with $\gamma_{n}=\min \left\{\frac{1}{32(n-2)}, \frac{1}{64}\right\}$ and $\tau=\varepsilon^{1 / 8}$ such that

$$
\int_{B_{\theta+\tau} \backslash B_{\theta}}\left|\nabla u^{h(x)}\right|^{2} \leq C \varepsilon^{\frac{1}{16}} \int_{B_{1}}|\nabla u|^{2}
$$

Claim 3: Since $u$ is minimizing,

$$
\int_{B_{\theta+\tau}}|\nabla u|^{2} \leq C \int_{B_{\theta+\tau}}\left|\nabla u^{h(x)}\right|^{2}
$$

Using Claims $1-3$ and noting $\theta \in[\bar{\theta}, 2 \bar{\theta}]$, we obtain

$$
\begin{aligned}
\theta^{2-n} \int_{B_{\theta}}|\nabla u|^{2} & \leq \theta^{2-n} \int_{B_{\theta+\tau}}|\nabla u|^{2} \\
& \leq C \theta^{2-n}\left(\int_{B_{\theta}}\left|\nabla u^{h}\right|^{2}+\int_{B_{\theta+\tau} \backslash B_{\theta}}\left|\nabla u^{h}\right|^{2}\right) \\
& \leq C\left(\theta^{2-n} \varepsilon^{\frac{1}{4}}+\theta^{2}+\varepsilon^{\frac{1}{16}}\right) \int_{B_{1}}|\nabla u|^{2} \leq C \varepsilon^{2 \gamma_{n}} \int_{B_{1}}|\nabla u|^{2} .
\end{aligned}
$$

Choosing $\varepsilon$ sufficiently small, the required result follows.
Claim 3 follows from Lemma 5.5. Next, we are going to prove Claims 1-2.

To prove Claim 1, let $v$ be the solution of

$$
\begin{aligned}
& \triangle v=0 \quad \text { in } B_{1 / 2} \\
& v=u^{\bar{h}} \quad \text { on } \partial B_{1 / 2} .
\end{aligned}
$$

By the maximal principle, we have

$$
\sup _{B_{1 / 2}}\left|v-u^{\bar{h}}\right| \leq C \varepsilon^{1 / 4}
$$

By the mean value inequality $\left(\triangle|\nabla v|^{2} \geq 0\right)$, we have

$$
\sup _{B_{1 / 4}}|\nabla v|^{2} \leq C \int_{B_{1 / 2}}|\nabla v|^{2} \leq C \int_{B_{1 / 2}}\left|\nabla u^{\bar{h}}\right|^{2} \leq C \int_{B_{1}}|\nabla u|^{2}
$$

Hence for any $\theta \in\left(0, \frac{1}{4}\right]$,

$$
\begin{align*}
\theta^{2-n} \int_{B_{\theta}}\left|\nabla u_{\bar{h}}\right|^{2} & \leq 2 \theta^{2-n} \int_{B_{\theta}}\left|\nabla\left(u_{\bar{h}}-v\right)\right|^{2}+2 \theta^{2-n} \int_{B_{\theta}}|\nabla v|^{2}  \tag{15}\\
& \leq 2 \theta^{2-n} \int_{B_{\theta}}\left|\nabla\left(u_{\bar{h}}-v\right)\right|^{2}+C \theta^{2} \int_{B_{1}}|\nabla u|^{2} . \tag{16}
\end{align*}
$$

Note

$$
\begin{aligned}
\Delta u^{h} & =\int_{\mathbb{R}^{n}}\left[\triangle_{x} \phi^{\bar{h}}(x-y)\right] u(y) d y \\
& \left.=\int_{\mathbb{R}^{n}}\left[\triangle_{y} \phi^{\bar{h}}(x-y)\right] u(y) d y\right]=\int_{\mathbb{R}^{n}} \phi^{\bar{h}}(x-y) \triangle_{y} u(y) d y \\
& \left.=\int_{\mathbb{R}^{n}} \phi^{\bar{h}}(x-y)\right] A(u)(\nabla u, \nabla u)(y) d y
\end{aligned}
$$

which implies

$$
\int_{B_{1 / 2}}\left|\triangle u^{\bar{h}}\right| \leq C \int_{B_{1}}|\nabla u|^{2}
$$

Then

$$
\begin{equation*}
\int_{B_{1 / 2}}\left|\nabla\left(u^{\bar{h}}-v\right)\right|^{2}=-\int_{B_{1 / 2}} \Delta u^{\bar{h}} \cdot\left(u^{\bar{h}}-v\right) \leq C \varepsilon^{1 / 4} \int_{B_{1}}|\nabla u|^{2} \tag{17}
\end{equation*}
$$

Claim 1 follows from (15) - (17).
Now we are going to prove Claim 2.
We recall $\bar{\theta}=\varepsilon^{\gamma_{n}}$ with $\gamma \leq \frac{1}{16}$. Let $l=\left[\frac{\bar{\theta}}{3 \tau}\right]\left(\geq \frac{1}{3} \varepsilon^{-\frac{1}{16}}-1\right)$ be the integer of $\frac{\theta}{3 \tau}$ and write

$$
[\bar{\theta}, \bar{\theta}+3 \tau l]=\cup_{1 \leq i \leq l} I_{i}, \quad\left|I_{i}\right|=3 \tau
$$

where each $I_{i}$ is a closed interval of length $3 \tau$. Since $\gamma_{n} \leq \frac{1}{16}, l \geq \frac{1}{3} \varepsilon^{-\frac{1}{16}}$. Then

$$
\int_{B_{\bar{\theta}+3 l \tau} \backslash B_{\bar{\theta}}}|\nabla u|^{2} d x=\sum_{1 \leq i \leq l} \int_{|x| \in I_{i}}|\nabla u|^{2} d x \leq \int_{B_{1}}|\nabla u|^{2} .
$$

There is at least one interval $I_{j}$ with $1 \leq j \leq l$ such that

$$
\int_{|x| \in I_{j}}|\nabla u|^{2} d x \leq l^{-1} \int_{B_{1}}|\nabla u|^{2} \leq C \varepsilon^{\frac{1}{16}} \int_{B_{1}}|\nabla u|^{2} .
$$

Let $\theta$ be the number such that $I_{j}=[\theta-\tau, \theta+2 \tau] \subset[\bar{\theta}, 2 \bar{\theta}]$, and let $h=h(x)$ be as in Lemma 5.3. Then $u_{h} \in W^{1,2}\left(B_{1 / 2}, N\right)$ and $u_{h}=u$ for any $|x| \geq \theta+\tau$, and

$$
\int_{B_{\theta+\tau} \backslash B_{\theta}}\left|\nabla u_{h}\right|^{2} \leq C \varepsilon^{\frac{1}{16}} \int_{B_{1}}|\nabla u|^{2} .
$$

This proves Claim 2.
As a consequence of this lemma, we can prove:
Theorem 5.7. Let $u \in W^{1,2}(M ; N)$ be a minimizer of $E(u)$ in $W^{1,2}(M ; N)$. Then, $u$ is smooth in $M \backslash \Sigma$, where $\Sigma$ is the singular set defined by

$$
\begin{equation*}
\Sigma=\left\{x \in M: \lim _{r \rightarrow 0} r^{2-n} \int_{B_{r}(x)}|\nabla u|^{2} \geq \varepsilon_{0}^{2}\right\} \tag{18}
\end{equation*}
$$

and $\mathcal{H}^{n-2}(\Sigma)=0$.

Proof. If $x_{0} \notin \Sigma$, then there is a $r_{0}>0$ such that

$$
r_{0}^{2-n} \int_{B_{r_{0}}\left(x_{0}\right)}|\nabla u|^{2} \leq \varepsilon_{0}^{2}
$$

implying

$$
\left(\frac{r_{0}}{2}\right)^{2-n} \int_{B_{r_{0}}(x)}|\nabla u|^{2} \leq 2^{n-2} \varepsilon_{0}^{2}, \quad \forall x \in B_{\frac{r_{0}}{2}}\left(x_{0}\right) .
$$

By the monotonicity, we have

$$
r^{2-n} \int_{B_{r}(x)}|\nabla u|^{2} \leq 2^{n-2} \varepsilon_{0}^{2} \leq \varepsilon, \quad \forall x \in B_{\frac{r_{0}}{2}}\left(x_{0}\right) \text { and } 0<r \leq \frac{r_{0}}{2}
$$

for $\varepsilon_{0}$ sufficiently small, where $\varepsilon$ is the constant in Lemma 5.6. By the above lemma, there is a $\theta \in(0,1)$ such that

$$
\theta^{2-n} \int_{B_{\theta}}|\nabla u|^{2} \leq \frac{1}{2} \int_{B_{1}}|\nabla u|^{2}
$$

We consider a rescaling map $u_{\theta}(x)=u(\theta x)$. Then

$$
\int_{B_{1}}\left|\nabla u_{\theta}\right|^{2}=\theta^{2-n} \int_{\theta}|\nabla u|^{2} \leq \varepsilon .
$$

Using again Lemma, we have

$$
\left(\theta^{2}\right)^{2-n} \int_{B_{\theta^{2}}}|\nabla u|^{2}=(\theta)^{2-n} \int_{B_{\theta}}\left|\nabla u_{\theta}\right|^{2} \leq \frac{1}{2} \int_{B_{1}}\left|\nabla u_{\theta}\right|^{2}=\left(\frac{1}{2}\right)^{2} \int_{B_{1}}|\nabla u|^{2}
$$

By the induction argument, we have

$$
\left(\theta^{i}\right)^{2-n} \int_{B_{\theta^{i}}}|\nabla u|^{2} \leq\left(\frac{1}{2}\right)^{i} \int_{B_{1}}|\nabla u|^{2} .
$$

For any $r \in(0,1)$, there is integer $i$ so that $r \in\left[\theta^{i+1}, \theta^{i}\right]$. Then

$$
r^{2-n} \int_{B_{r}(x)}|\nabla u|^{2} \leq C\left(\theta^{i}\right)^{2 \alpha} \int_{B_{1}}|\nabla u|^{2} \leq C r^{2 \alpha} \int_{B_{1}}|\nabla u|^{2}
$$

for some $\alpha=\log 2 /\left(2 \log \theta^{-1}\right)>0$. Repeating the above arguments, we can obtain

$$
r^{2-n} \int_{B_{r}(x)}|\nabla u|^{2} \leq C r^{2 \alpha}, \quad \forall x \in B_{r_{0} / 2}\left(x_{0}\right) \text { and } 0<r \leq \frac{r_{0}}{2}
$$

for some $\alpha \in(0,1)$ depending on $\varepsilon_{0}, M$ and $N$. By Morrey's Lemma, $u \in C^{\alpha}\left(B_{r_{0} / 2}\left(x_{0}\right), N\right)$.

Next we will show $\mathcal{H}^{n-2}(\Sigma)=0$.
Since $M$ is compact and $\Sigma$ is relatively closed, by Vitali's covering lemma (see Giaquinta's book [9] ), there are disjoint balls $\left\{B_{r_{i}}\left(x_{i}\right)\right\}_{i \in I}$ such that

$$
\Sigma \subset \cup_{i} B_{3 r_{i}}\left(x_{i}\right), \quad r_{i} \leq \delta
$$

so

$$
\mathcal{H}_{5 \delta}^{n-2}(\Sigma) \leq \sum_{i \in I}\left(5 r_{i}\right)^{n-2} \leq \frac{5^{n-2}}{\varepsilon_{0}^{2}} \int_{\cup_{i \in I} B_{r_{i}}\left(x_{i}\right)}|\nabla u|^{2} d x \leq C \int_{M}|\nabla u|^{2}<+\infty .
$$

Note

$$
\text { meas }\left|\cup_{i \in I} B_{r_{i}}\left(x_{i}\right)\right| \leq C \delta^{2}
$$

Hence $\mathcal{H}^{n-2}(\Sigma)=0$ by letting $\delta \rightarrow 0$.
Lemma 5.8. Let $u_{i} \in W^{1,2}(\Omega, N)$ be a sequence of minimizing harmonic maps. If $u_{i} \rightarrow u$ weakly in $W^{1,2}(\Omega, N)$, then $u_{i} \rightarrow u$ strongly in $W_{l o c}^{1,2}(\Omega, N)$ and $u$ is a minimizing harmonic map.

The proof is based on the application of Luckhaus's Lemma. (We omit details and refer to see Leon Simon's book [31] or Lin-Wang's book [22])

Next we will prove the Hausdorff dimension of the singular set is $n-3$.
Following [28], we define

$$
\varphi^{p}(E)=\inf \left\{\sum_{i} r_{i}^{s}: E \subset \cup_{i} B_{r_{i}}\left(x_{i}\right)\right\}
$$

Then

$$
\varphi^{p}(E)=0 \text { if and only if } \mathcal{H}^{p}(E)=0
$$

Moreover, if $\varphi^{s}(E)>0$, then the following density result of Federer holds:

$$
\limsup _{\lambda \rightarrow 0} \lambda^{-s} \varphi^{s}\left(E \cap B_{\lambda}\right) \geq c>0
$$

for $\varphi^{s}$ a. e. $x \in E($ see [28] $)$.
Lemma 5.9. Suppose $u_{i}$ is a sequence of minimizing maps in $W^{1,2}(M, N)$, which converges weakly to $u$ in $W^{1,2}$. Let $\Sigma_{i}$ be the singular set of $u_{i}$ and $\Sigma$ denotes the singular set of $u$. Then we have

$$
\varphi^{s}\left(\Sigma \cap B_{1}\right) \geq \limsup _{i \rightarrow 0} \varphi^{s}\left(\Sigma_{i} \cap B_{1}\right)
$$

for any $s \geq 0$

We complete the proof of Theorem 5.2.
Proof. Suppose $u \in W^{1,2}(M, N)$ is a minimizing harmonic map with the singular set $\Sigma \subset$ int M. Let $0 \leq s<n-2$ be such that $\varphi^{s}(\Sigma)>0$. Then by the density result, we can choose $x_{0} \in \Sigma$ such that

$$
\lim _{\lambda_{i} \rightarrow 0} \lambda_{i}^{-s} \varphi^{s}\left(\Sigma \cap B_{\lambda_{i}}\left(x_{0}\right)\right)>0
$$

for a sequence of $\lambda_{i} \rightarrow 0$. Then we consider the scaled maps $u_{\lambda}(x)=u(\lambda x)$. By the monotonicity formula (Lemma 5.3) and Theorem 5.9, $u_{\lambda_{i}}$ converges to a minimizing harmonic map $u_{0}$ weakly in $W^{1,2}\left(B_{2}, N\right)$ and strongly in $W^{1,2}\left(B_{1}\right)$. Note that $\varphi^{s}\left(\Sigma_{\lambda} \cap B_{1}\right)=\lambda^{-s} \varphi^{s}\left(\Sigma \cap B_{1}\right)$. The density result implies

$$
\lim _{\lambda_{i} \rightarrow 0} \varphi^{s}\left(\Sigma_{\lambda_{i}} \cap B_{1}\right)>0
$$

By Lemma 5.9, we obtain

$$
\varphi^{s}\left(\Sigma \cap B_{1}\right)>0 .
$$

Since $\frac{\partial u_{0}}{\partial r}=0$, we have $\lambda \Sigma_{0} \subset \Sigma_{0}$ for any $\lambda>0$.
There are two cases: either $s \leq 0$ or there is a point $x_{1} \in \Sigma_{0} \cap \partial B_{1}$ such that

$$
\limsup _{\lambda \rightarrow 0} \lambda^{-s} \varphi^{s}\left(\Sigma_{0} \cap B_{\lambda}\left(x_{1}\right)\right)>0
$$

Then repeating the above argument at $x_{1}$, there is a radially symmetric minimizing harmonic map $u_{1}$ with $\phi^{s}\left(\Sigma_{1} \cap B_{1}\right)>0$, where $\Sigma_{1}$ is the singular set of $\Sigma_{1}$. If $s-1 \leq 0$, we stop. Otherwise, we repeat the above argument so that there is a point $x_{2} \in \Sigma_{1} \cap \partial B_{1}$. If we repeat this procedure $m$ times, we get minimizing harmonic maps $u_{j} \in W^{1,2}\left(\mathbb{R}^{n}, N\right)$ for $j=1, \ldots, m$ such that $\frac{\partial u_{j}}{\partial x^{k}}=0$ for $k=1, \ldots, j$. By the construction $u_{m}$, it must have that $s-m+1>0$ and $s \leq m$. Since $s<n-2$ and $m$ is an integer, then $m \leq n-2$. If $m=n-2$, then we have

$$
\Sigma_{m} \supset \mathbb{R}^{n-2}=\left\{\left(x^{1}, \ldots, x^{n-2}, 0,0\right)\right\}
$$

which contradicts with the fact that $\mathcal{H}^{n-2}\left(\Sigma_{m}\right)=0$. Therefore, we have $m \leq n-3$. Hence $\varphi^{t}\left(\Sigma \cap B_{1}\right)=0$ for all $t \geq n-3$. This implies that $\operatorname{dim} \Sigma \leq n-3$.

In fact, Leon Simon 31] (also also 22]) presented another beautiful proof based on the ideas of Almgren.

## 6. Further Developments

In this section, we would like to make a few remarks about harmonic maps and related topics.

1. Minimizing harmonic maps:

Leon Simon 30] proved the rectifiablity of the singular set of minimizing harmonic maps.
2. Partial regularity result on Stationary harmonic maps:

Partial regularity result on Stationary harmonic maps have been established by Bethuel [1]. A new approach was presented by Riviere-Struwe [25]. Lin [21] established a result on the structure of the singular set.

## 3. Heat flow for Harmonic maps:

Struwe 32] proved the global existence of the weak solution to the harmonic map flow and that the solution to the flow converges to a harmonic map as $t \rightarrow \infty$. Chang, Ding and Ye [3] constructed an example where the harmonic map flow blows up at finite time. Chen-Struwe [5] (also 22]) used the Ginzburg-Landau approximation to establish the global existence and partial regularity of the harmonic map flow. Recently, Hong-Yin 17] introduced the Sack-Uhlenbeck flow in 2D to establish new existence of the harmonic map flow.
4. Relaxed energy for harmonic maps and a new approximation approach:

Bethuel-Brisis-Coron 2] introduced the relaxed energy functional. Giaquinta-Modica-Soucek [12] proved the partial regularity using Cartesian currents. Giaquinta-Hong-Yin [11] proposed a new approximation method to prove the partial regularity.
5. Biharmonic maps between manifolds:

Partial regularity of stationary bi-harmonic maps was established by Chang-Wang-Yang [4], Wang [36] and Struwe [33]. Recently, Hong and Yin [16] solved a problem on the relaxed energy for biharmonic maps.

## References

1. F. Bethuel, On the singular set of stationary harmonic maps, Manus. Math., 78(1993), 417-443.
2. F. Bethuel, H. Brezis and J. M. Coron, Relaxed energies for harmonic maps, In variational methods, edited by Berestycki, Coron, Ekeland, Birkhäuser, Basel (1990), 37-52.
3. K. C. Chang, W. Y. Ding and R. Ye, Finite-time blow-up of the heat flow of harmonic maps from surfaces, J. Differential Geom., 36 (1992), no.2, 507-515.
4. S. Y. A. Chang, L. Wang and P. Yang, A regularity theory of biharmonic maps, Comm. Pure Appl. Math., 52 (1999), 1113-1137.
5. Y. M. Chen and M. Struwe, Existence and partial regularity for heat flow for hamonic maps, Math. Z., 201 (1989), 83-103.
6. S. K. Donaldson, Anti-self-dual Yang-Mills connections on complex algebraic surfaces and stable vector bundles, Proc. Lond. Math. Soc., 50 (1985), 1-26.
7. J. Eells and J. H. Sampson, Harmonic mappings of Riemannian manifolds, Amer. J. Math., 86 (1964), 109-160.
8. J. Eells and L. Lemaire, A report on harmonic mapps, Bull. London Math. Soc., 10 (1978), 1-68.
9. M. Giaquinta, Multiple integrals in the calculus of variations and nonlinear elliptic systems, Annals of Mathematics Studies, 105. Princeton University Press, Princeton, NJ, 1983.
10. M. Giaquinta and E. Giusti: The singular set of the minima of certain quadratic functional, Ann. Scuola Norm. Sup. Pisa, 11 (1984), 45-55.
11. M. Giaquinta, M.-C. Hong and H. Yin, A New Approximation of Relaxed Energies for Harmonic Maps and the Faddeev Model, Calculus of Variations and Partial Differential Equations, 41 (2011), 45-69.
12. M. Giaquinta, G. Modica and J. Soucek, The Dirichlet energy of mappings with values into the sphere, Manus. Math., 65 (1989), 489-507.
13. D. Gilbarg and N. Trudinger, Elliptic Partial Differential Equations of Second Order, Second edition. Springer-Verlag, Berlin, 1983.
14. R.S. Hamilton, Three manifolds with positive Ricci curvature, J. Differential Geom., 17 (1982), 255-306.
15. P. Hartman, On homotopic harmonic maps, Canad. J. Math., 19 (1967), 673-687.
16. M.-C. Hong and H. Yin, Partial regularity of a minimizer of the relaxed energy for biharmonic maps, J. Functional Analysis, 262 (2012), 682-718.
17. M.-C. Hong and H. Yin, On the Sacks-Uhlenbeck flow of Riemannian surfaces, Communications in Analysis and Geometry, 21 (2013), 917-955.
18. J. Jost, Nonlinear methods in Riemannian and Kählerian geometry, DMV seminar, Band 10, Birkäuser, Basel-Boston-Berlin, 1991.
19. L. Lemaire, Applications harmoniques des surfaces Riemanniennes, J. Differential Geom., 13 (1978), 51-78.
20. Y. X. Li and Y. D. Wang, A weak energy identity and the length of necks for a sequence of Sacks-Uhlenbeck $\alpha$-harmonic maps, Adv. Math., 225 (2010), 1134-1184.
21. F.-H. Lin, Gradient estimates and blow-up analysis for stationary harmonic maps, Ann. Math., 149 (1999), 785-829.
22. F. H. Lin and C. Y. Wang, The Analysis of Harmonic Maps and Their Heat Flows, World Scientific Publishing Co. Pte. Ltd., 2008.
23. J. Moser, On Harnack's theorem for elliptic differential equations, Comm. Pure Appl. Math., 14 (1961), 577-591.
24. T. Riviere, Everywhere discontinuous harmonic maps into spheres, Acta Math., 175 (1995), 197-226.
25. T. Riviere and M. Struwe, Partial regularity for harmonic maps and related problems, Comm. Pure Appl. Math., 61 (2008), 451-463.
26. J. Sacks and K. Uhlenbeck, The existence of minimal immersions of 2-spheres, Ann. of Math., 113 (1981), 1-24.
27. R. Schoen, Analytic aspects of the harmonic map problem, Seminar on nonlinear partial differential equations (Berkeley, Calif., 1983), 321-358, Math. Sci. Res. Inst. Publ., 2, Springer, New York, 1984.
28. Schoen, R. and Uhlenbeck, K., A regularity theory for harmonic maps, J. Diff. Geom., 17(1982), 305-335.
29. R. Schoen and S. T. Yau, Existence of incompressible minimal surfaces and the topology of three dimensional manifolds with non-negative scalar curvature, Ann. of Math., 110 (1979), 127-142.
30. L. Simon, Rectifiablity of the singular set of energy minimizing maps, Calc. Var. © P. D. E., 3 (1995), 1-65.
31. L. Simon, Theorems on Regularity and Singularity of Energy Minimizing Maps, Berlin, Birkhäuse, 1996.
32. M. Struwe, On the evolution of harmonic maps of Riemannian surfaces, Comm. Math. Helv., 60 (1985), 558-581.
33. M. Struwe, Partial regularity for biharmonic maps, revisited, Calc. Var. \& PDE, 33 (2008), 249-262.
34. N. Trudinger, Harnack inequalities for nonuniformly elliptic divergence structure equations, Invent. Math., 64 (1981), 517-531.
35. K. Uhlenbeck, Regularity for a class of non-linear elliptic systems, Acta Math., 138 (1977), 219-240.
36. C. Y. Wang, Stationary biharmonic maps from $\mathbb{R}^{m}$ into a Riemannian manifold, Comm. Pure Appl. Math., 57 (2004), 419-444.
